



Pressure Definitions

Absolute

- Total static pressure exerted by gas/fluid
- Barometric pressure

Gauge

- Pressure relative to atmospheric pressure
- e.g., pressure in a tire

Differential

- Pressure relative to another pressure
- Gauge pressure is a special case of differential pressure

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Let's make an instrument: Manometer

$$h = \frac{P_2 - P_1}{\rho_{\text{fluid}} g}$$

P_1 – ambient pressure (not necessarily atmospheric pressure)
 P_2 – gauge pressure

Here, we're measuring differential pressure (two unknown pressures). In meteorology, we want to measure the absolute pressure...

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Let's make an instrument: Manometer

To measure atmospheric pressure, we close off one end of the manometer tube.

$$h = \frac{P}{\rho_{\text{fluid}} g}$$

In normal operation, we straighten out the tube, invert it, and place the open end in a reservoir of mercury

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Mercury Barometers

Fig. 2-2 A simple mercury barometer.

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Mercury (Fortin) Barometers

■ The Fortin design:

- Level of cistern maintained at zero of scale
- High accuracy
- Easy calibration
- Mercury enclosed in a glass tube that is sealed at the top
 - Almost a vacuum
 - Pressure = vapor pressure of Hg + residual gas
- Mercury reservoir at the bottom
- Level of mercury in reservoir is adjusted to a reference (fiducial) point

Fig. 2-2 A simple mercury barometer.

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Vernier Scale

10 VERNIER

20 VERNIER

What is the reading for each of these vernier scales?
No peaking...

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Mercury Barometer Errors: Non-uniformity of temperature

- Mercury is used in thermometers because it expands and contracts with changes in temperature
- Temperature gradients along the mercury column can vary that expansion or contraction in an unknown manner
- Most Fortin barometers are housed in a closed environment to prevent temperature (but not pressure) fluctuations

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Mercury Barometer Errors: Dirt

- Dirty mercury
 - Difficult to see when the fiducial point touches the mercury
 - Hard to read the meniscus
 - Impurities can affect density
- Dirty scale
 - Hard to read the scale
 - Corrosion could affect the expansion coefficient

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Mercury Barometer Errors: Barometer not mounted vertically

- Typically small errors
- At 1000 mb, barometer must be kept within 1.5 mm of vertical in order to keep error to within 0.026 mb.

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Mercury Barometer Errors: Gas in the vacuum space

- The pressure of any gas in the vacuum space will tend to counteract the pressure being exerted by the atmosphere
- If we tilt the barometer, a true vacuum won't create a bubble
- What can get in there?
 - Mercury vapor – very small error (low vapor pressure)
 - Air
 - Water vapor – potentially large error
 - 10 μg of water vapor can potentially cause a 2.3-mb error at normal atmospheric pressures

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Mercury Barometer Errors: Capillary depression of the mercury surface

- This error is typically small and known
- Narrowing of the tube can cause changes to the mercury meniscus

- For a 5 mm diameter tube, the error can be as large as 2.00 mb
- For a 13 mm diameter tube, the error can be as large as 0.27 mb
- Correction for this error is incorporated into the **index correction**

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Mercury Barometer Errors: Index Correction

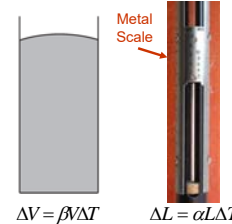
- The index correction (C_x) is a table of corrections that account for slight imperfections of the tube diameter and vacuum that are inevitable during manufacture
- Values are supplied to the user by the manufacturer
 - Assume $C_x = 0$ if not specified
- Values are found by calibrating the instrument with a reference instrument



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Mercury Barometer Errors: Temperature Correction

- Changes in temperature can affect the expansion and contraction of the mercury column and the attached metal scale



$$C_T = -p_1(\beta - \alpha)T$$

The pressure error is a function of the difference between the change in the column height and linear expansion of the scale due to changes in temperature.

Here, T is the temperature in °C and p_1 is the measured pressure.

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Mercury Barometer Errors: Correctable Error

- Now we have two corrections that we can apply to improve the pressure measurement:

$$p_2 = p_1 + C_x + C_T$$

p_1 = Barometer reading
 C_x = Index correction
 C_T = Temperature correction



But wait, there's more... Watch this!

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Mercury Barometer Errors: Gravity Correction

- Gravity is not constant!
 - We must correct for local gravity with respect to gravity at mean sea level

$$C_G = p_2 \left(\frac{g_L - g_0}{g_0} \right) \quad g_0 = 9.80665 \frac{m}{s^2}$$

- Local gravity, g_L , changes with elevation:

$$g_L = g_\phi - 3.086 \times 10^{-6} z + 1.118 \times 10^{-6} (z - z')$$

z = barometer elevation (m)

z' = mean elevation (m) within a 150 km radius

- Since Earth is not a sphere, gravity at sea level varies with latitude, ϕ :

$$g_\phi = 9.80616 \left[1 - 2.6373 \times 10^{-3} \cos(2\phi) + 5.9 \times 10^{-6} \cos^2(2\phi) \right]$$

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Mercury Barometer Errors: Correctable Error

- The best estimate of surface pressure is then:

$$p_{sfc} = p_1 + C_x + C_T + C_G$$

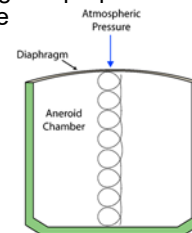
p_1 = Barometer reading
 C_x = Index correction
 C_T = Temperature correction
 C_G = Gravity correction

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Aneroid Barometer

- Aneroid: without fluid
 - a- (without) + nero- (water) + -oid (resembling)
- Evacuated chamber with a flexible diaphragm
- Deflection of diaphragm is proportional to atmospheric pressure

The spring keeps the diaphragm from collapsing



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Aneroid Barometer

Calibration equation for a flat diaphragm

$$p = \frac{16Et^4}{3R^4(1-\nu^2)} \left[\frac{y}{t} + 0.488 \left(\frac{y}{t} \right)^3 \right]$$

p = pressure (Pa)

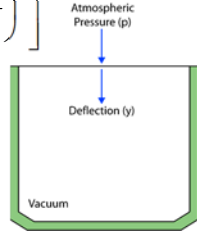
E = modulus of elasticity (N m^{-2})

y = deflection of the diaphragm center (m)

t = diaphragm thickness (m)

R = diaphragm radius (m)

ν = Poisson's ratio (related to ratio of lateral to axial strain) $\approx 1/3$ for metals



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Aneroid Barometer

Calibration equation for a flat diaphragm

- Define the deflection ratio as the ratio of the diaphragm deflection to the diaphragm thickness:

$$y_r = \frac{y}{t}$$

- Substitute into calibration equation for flat diaphragm aneroid cell:

$$p = C_0 [y_r + C_1 y_r^3]$$

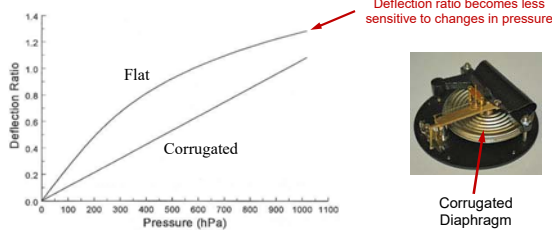
- C_0 and C_1 are the constant values from the calibration equation
- The relationship between y_r and p is non-linear.

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Aneroid Barometer

Static sensitivity

- Adding corrugations vastly improves linearity and increases **static sensitivity** at higher pressures



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Aneroid Barometer

Transfer equation for a corrugated diaphragm

$$y_r = \frac{y}{t} = \frac{2.25 \times 10^5 D (1-\nu^2)}{tE} \left(1000 \frac{t}{D} \right)^{-1.52} p$$

p = pressure (Pa)

E = modulus of elasticity (N m^{-2})

y = deflection of the diaphragm center (m)

t = diaphragm thickness (m)

R = diaphragm radius (m)

ν = Poisson's ratio (related to ratio of lateral to axial strain) $\approx 1/3$ for metals

$D = 2R$

$$y_r \sim (\text{constant}) p$$

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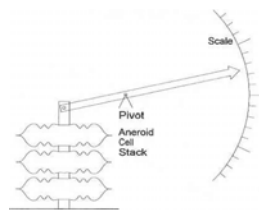
Aneroid Barometer

Mechanical Output

Deflection of a single aneroid is typically small; multiple chambers amplify the deflection



Aneroid Barograph



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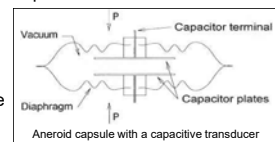
Aneroid Barometer

Electrical Output

- Piezoresistor**
 - Resistance changes in response to an applied force that deforms the resistor
- Capacitive transducer**
 - As diaphragm deflects, the distance between capacitor plates changes, changing the capacitance

$$C = \frac{\epsilon_0 A}{d}$$

- C = capacitance
- ϵ_0 = permittivity of free space
- A = area of plate
- d = distance between plates

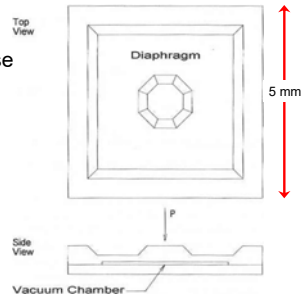


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Aneroid Barometer

Electrical Output

- Most barometers in use today are aneroid
 - Silicon diaphragm
 - Very small
 - Low leakage (excellent vacuum)
 - Linear deflection
 - Can compensate for temperature-induced errors (mostly)

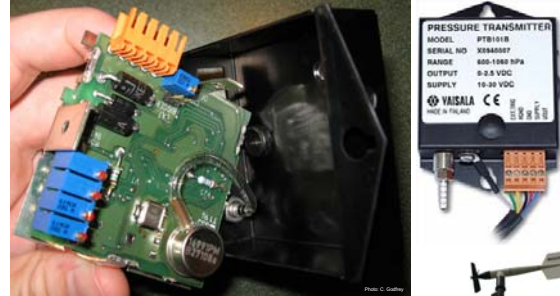


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Aneroid Barometer

Vaisala PTB101B Pressure Transmitter

Uses a silicon capacitive pressure transducer



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Current Barometric Measurements

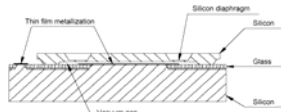
ASOS: Setra Model 470

Range: 600–1100 mb
Inaccuracy: ±0.02% full scale
Resolution: 0.01 mb



Oklahoma Mesonet: Vaisala PTB220

Range: 500–1100 mb
Inaccuracy: ±0.25 mb
Resolution: 0.1 mb



Inside the Vaisala PTB220

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Current Barometric Measurements

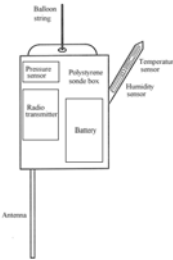
Vaisala RS80 Radiosonde

Range: 3–1060 mb
Inaccuracy: ±0.5 mb
Resolution: 0.1 mb

Used in twice daily NWS soundings



Vaisala's latest radiosonde: RS92



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Dynamic Wind Effects

- We usually want to measure only the **static pressure**
- **Dynamic pressure** affects all barometers and is due to air motion around the barometer
- To avoid the influence of pressure variations inside buildings (due to ventilation systems, open windows, closing doors, etc.), these errors can be reduced using a pressure vent to the outside (a static port)

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Dynamic Wind Effects

$$\Delta p = p - p_s = \frac{1}{2} C \rho V^2$$

- ρ is the air density
- V is the fluid speed
- C is the pressure coefficient
 - Usually close to unity
 - Positive or negative
 - Depends on shape of barometer and wind direction
 - Accounts for problems coupling the sensor to the atmosphere
- p is the pressure measured at the sensor
- p_s is the ambient atmospheric pressure



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Dynamic Wind Effects

- Dynamic wind effects are responsible for large pressure errors (an exposure error)

- Consider this...

You are driving a mobile mesonet vehicle at 25 m s^{-1} into a rear flank downdraft that has a surface wind speed of 30 m s^{-1} (directly toward the vehicle). What is the dynamic wind error in the pressure measurement? (Let $C=1$)

This is a huge error!

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Static Pressure Port

We need a device that will remove the dynamic wind effects and will allow a measurement of static pressure without error

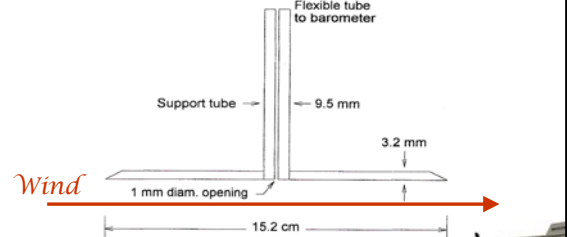
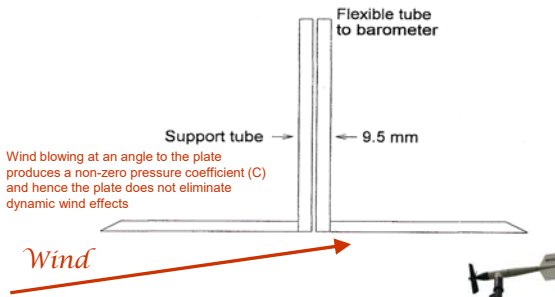


Fig. 2-13 Cross-section of a flat-plate static port.

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Static Pressure Port

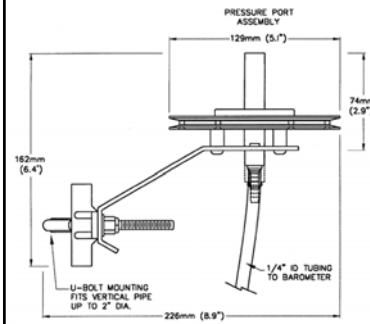
This is nice, but the flat plate has a problem when the wind is incident upon the port at an angle



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Dual-Plate Static Pressure Port

To improve upon this direction problem, engineers devised a dual-plate port



- Used in buoys
- Mounted vertically
- Better error results

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Quad-Plate Static Pressure Port

Another design further reduces angle errors



- Used in VORTEX
- Mounted upside down
- Even better error results

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